

Multi-stage, Multi-school Electric Bus Routing and Scheduling Optimization using Hybrid Metaheuristics

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Introduction

Scenarios

- US school bus system: largest form of public transportation by feet size
- <1% of fleets are electrified
- Responsible for 5 Mn tons of emission annually
- Multiple schools in a single school district
- Transitioning diesel buses to electric buses is hindered due to high capital investment, range anxiety, and an efficient operational system

Motivation

- Accelerated electrification through capital & operational cost optimization under practical constraints
- Innovative solution algorithm for NP-hard network optimization problems
- High priority but less explored research area



Fig: Diesel bus emission

Objectives

- Integrated solution for dynamic bus route optimization, timetabling and scheduling for multiple schools
- Novel integrated hybrid metaheuristics algorithm design for NP-hard network modeling problems
- Decision making process for school district on student transport electrification

Constraints

Routing Constraints

- Bus stop visit
 - Charging station visit
- ### Schedule Constraints
- Staggered school bell times
 - Bus re-use and charging at school
 - Student stop time window



Range Constraints

- Battery state of charge (SoC)
- Upper & lower battery bound

Bus capacity Constraint

Deadhead travel

Fast Charging Constraints

- Location & charging time

Problem Setting

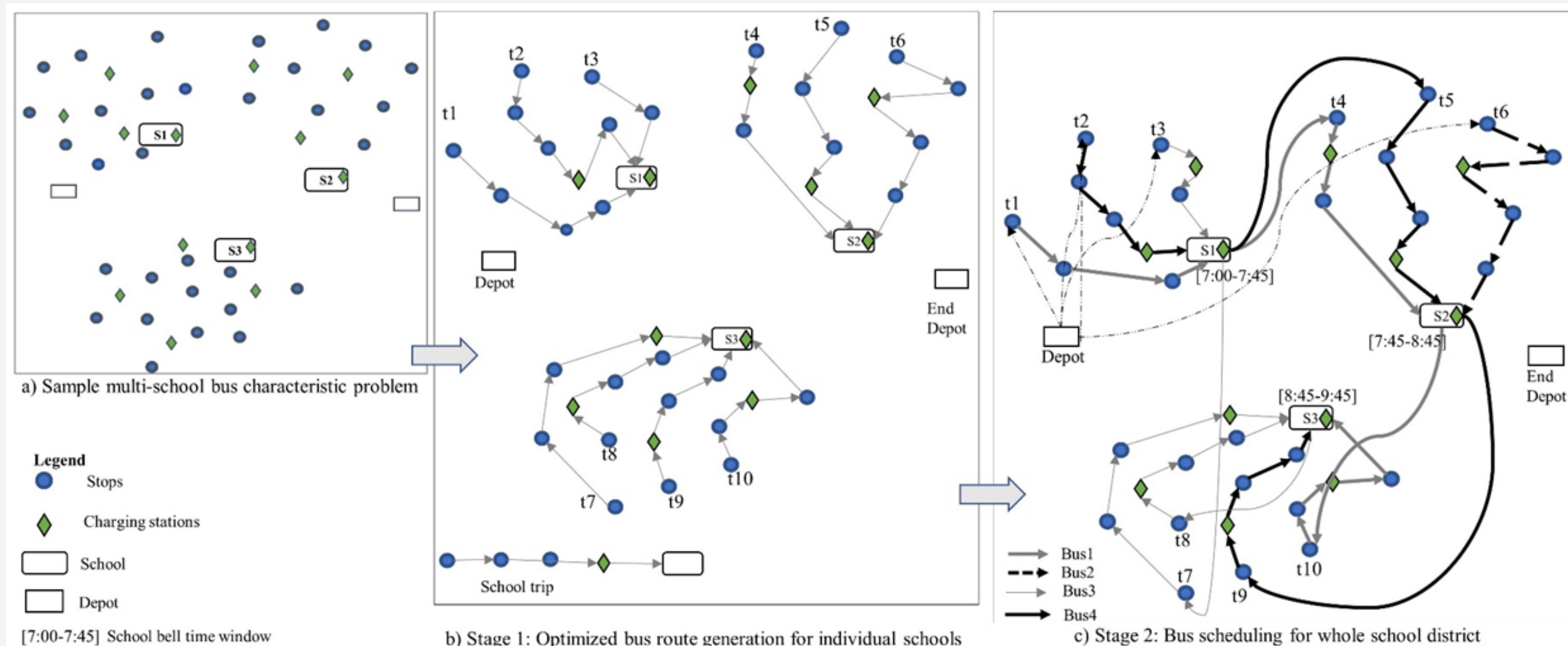


Figure: Typical school district student stops, stage wise optimization process

Mathematical Model Formulation

Stage-1: Route generation model formulation

$$\text{Min} \sum_{i \in V_0^r, j \in V_E^r} t_{ij} x_{ij}^k + \sum_{k \in K} (c_r + g c_t^k) \sum_{i \in F, j \in V_E^r} (B^k - v_i^k) z_i^k$$

Subject to,

- Student stop visit constraints
- Route start and end at depot constraints
- Fleet conservation constraints
- Travel time and stop time windows constraints
- Bus capacity constraints
- Battery consumption and battery bounds constraints
- Optimal charging location selection constraints

Stage-2: Multiple school bus scheduling MIP model formulation

$$\text{Min } Ob_1 + Ob_2 + Ob_3$$

$$Ob_1 = \sum_{k \in K} f^k \sum_{j \in \Delta^+ \setminus E} x_{0j}^k \quad [\text{Fleet cost component for multi-school bus service}]$$

$$Ob_2 = \sum_{k \in K} c_t^k \sum_{i \in S, j \in S^+} d_{ij} x_{ij}^k \quad [\text{Deadhead distances for buses in transition}]$$

$$Ob_3 = \sum_{k \in K} (c_r + g c_t^k) \sum_{i \in S, j \in \Delta^+} \varphi_i^k y_i^k \quad [\text{Charging and dwelling time cost in between services}]$$

Subject to,

- Staggered school bell times
- Bus charging at schools and bus re-use constraints
- Charging and travel time constraints

Hybrid Metaheuristics Approach

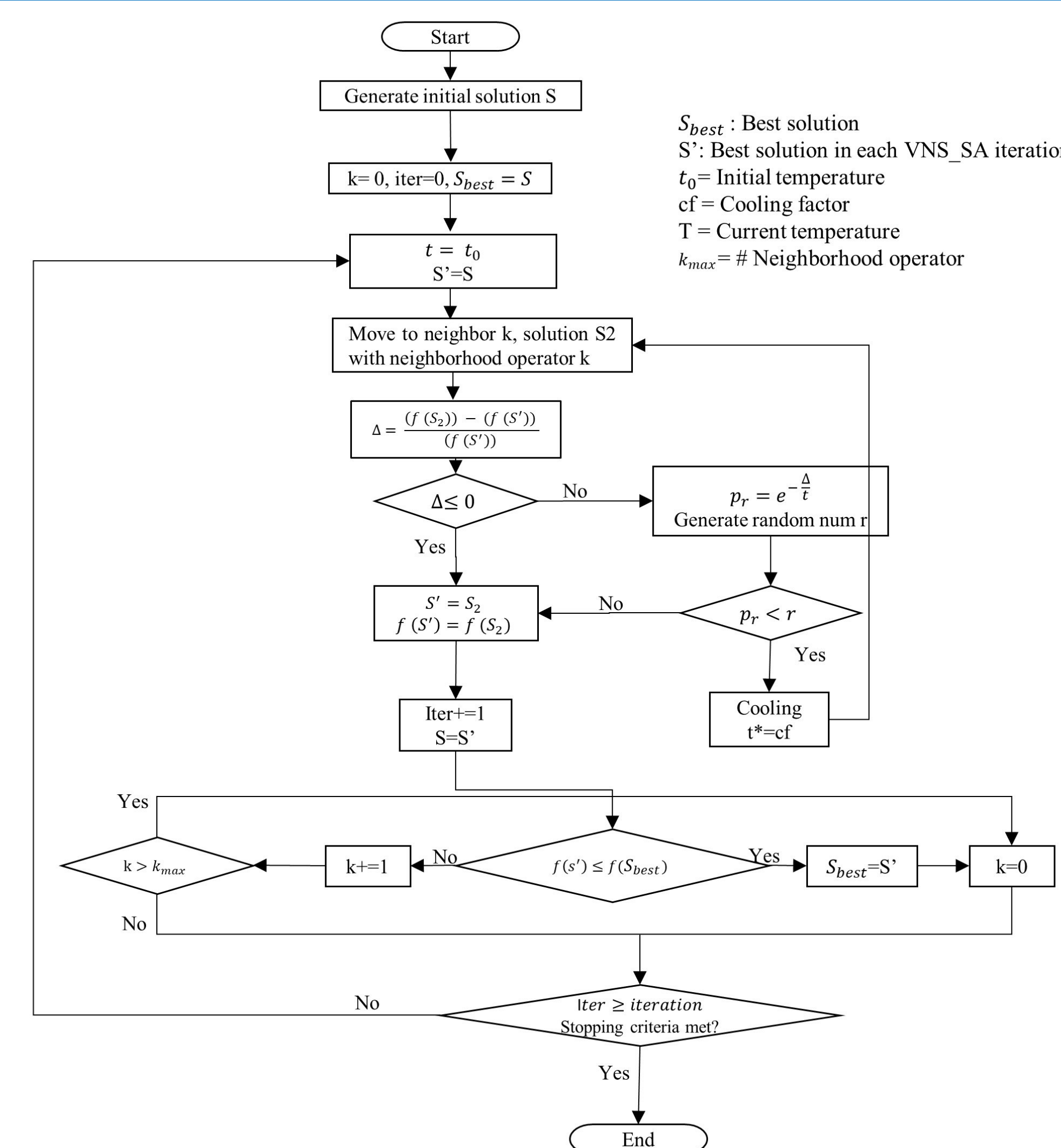


Figure: Metaheuristics implementation flowchart

Test Case Results for Stage1 and Stage 2

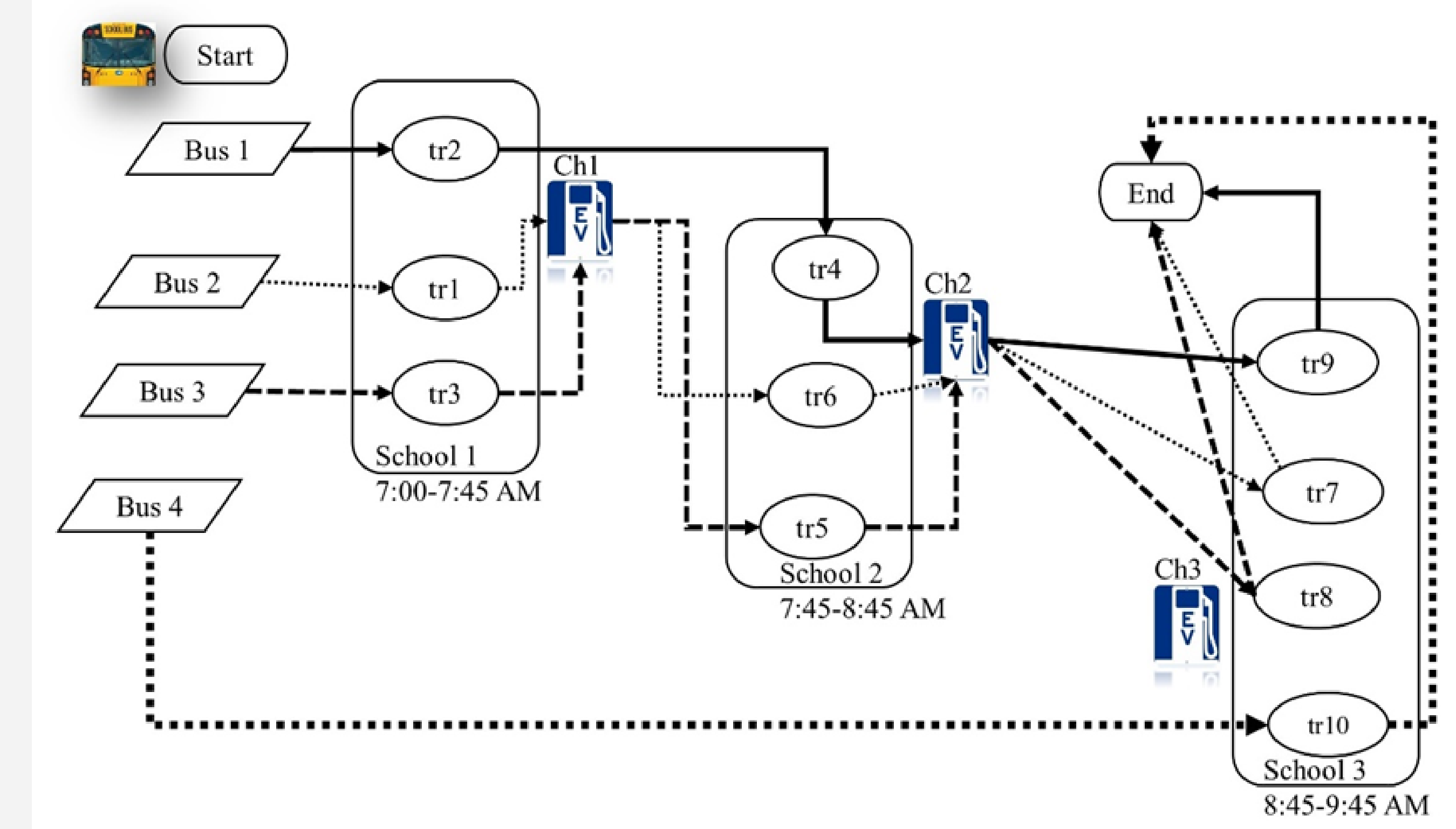
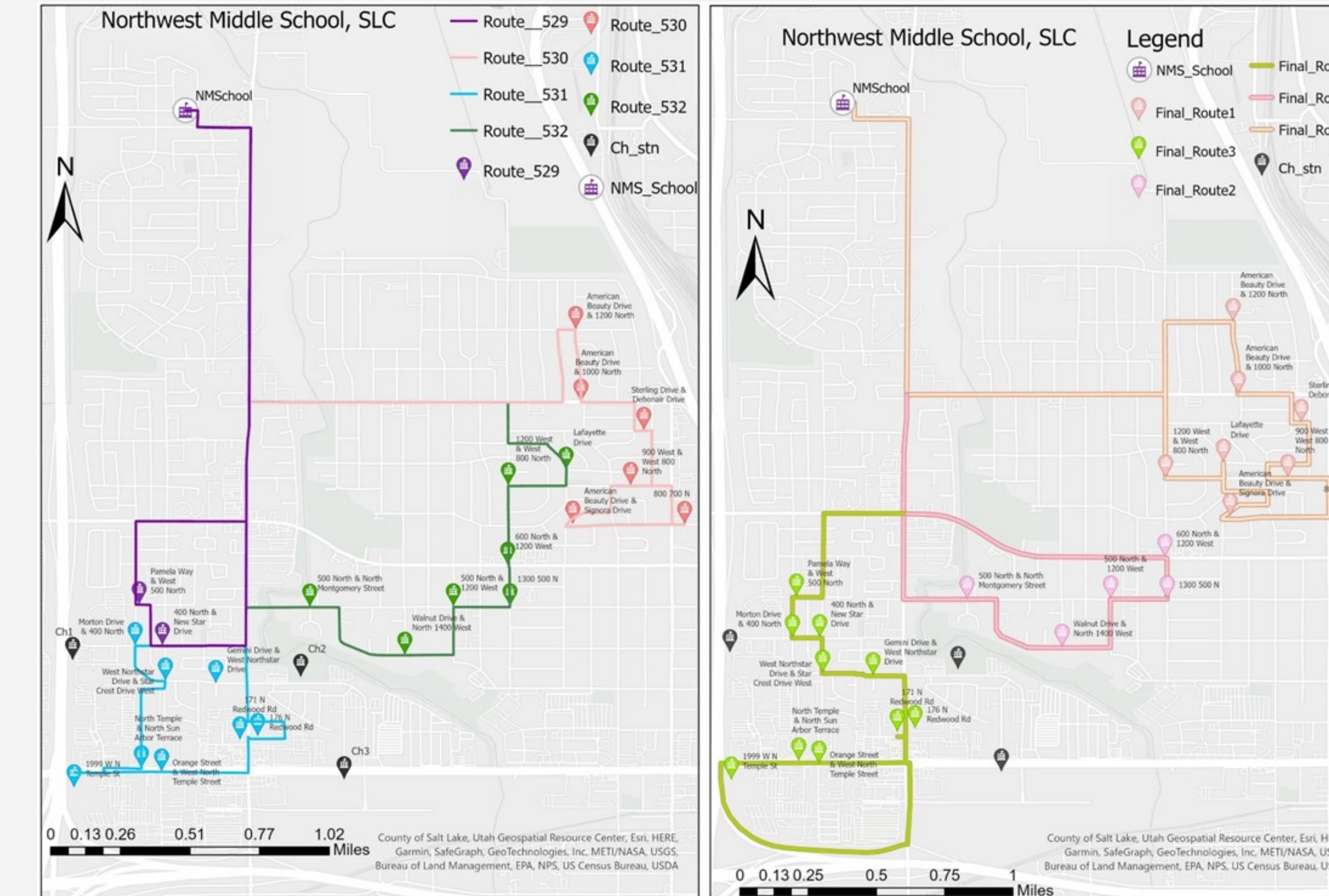


Figure: Model results for small network and case studies in both stages

Real World Case Study Result

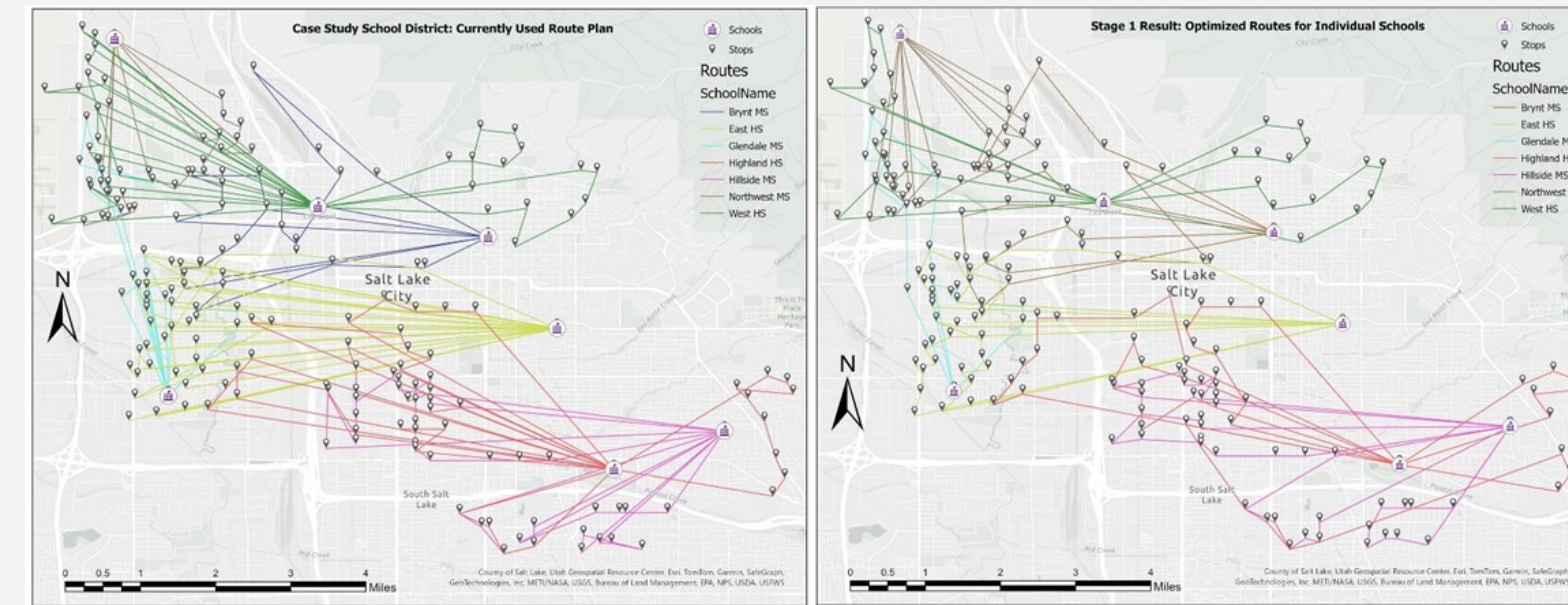


Figure: Salt Lake City school district case study and result improvement

Conclusion & Way Forward

- A new shift toward school bus electrification ESBP was solved through simultaneous routing, scheduling, and charging operation
- Novel hybrid VNS-SA metaheuristics designed for large scale networks
- Multi stage multi school algorithm successfully solved more than 10,000 nodes problem outperforming the existing NP hard algorithms
- Real world case study showed the school district can save up to 37% of fleets for fully electrify their existing fleets

⇒ Inclusion of non-linear charging functions, candidate charging station installation and charger types could be the next step advancing research

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